

EtherCAT for Factory Networking

EtherCAT Automation Protocol (EAP)

EtherCAT[®]
Automation Protocol



System Architecture

- | Fieldbus Network
- | Factory Network

ECAT Automation Protocol

- | Protocol

Process Data

Communication

- | Transfer Modes
- | Process Data Structure

Mailbox

Communication

- | Mailbox Data Structure
- | Object Dictionaries

Conclusion

1. System Architecture

- Fieldbus Network (EtherCAT)
- Factory Network (EtherCAT Automation Protocol)

2. EAP | EtherCAT Automation Protocol

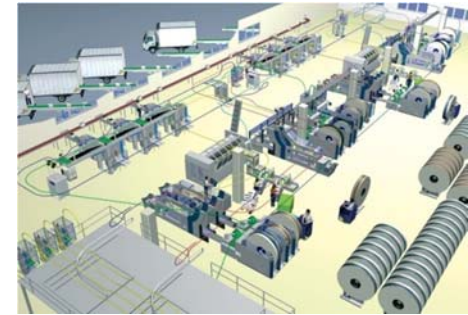
- Protocol

3. EAP | Process Data Communication

- Transfer Modes
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4. EAP | Mailbox Communication

- Mailbox Data Structure
- Object Dictionaries



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Process Data Communication

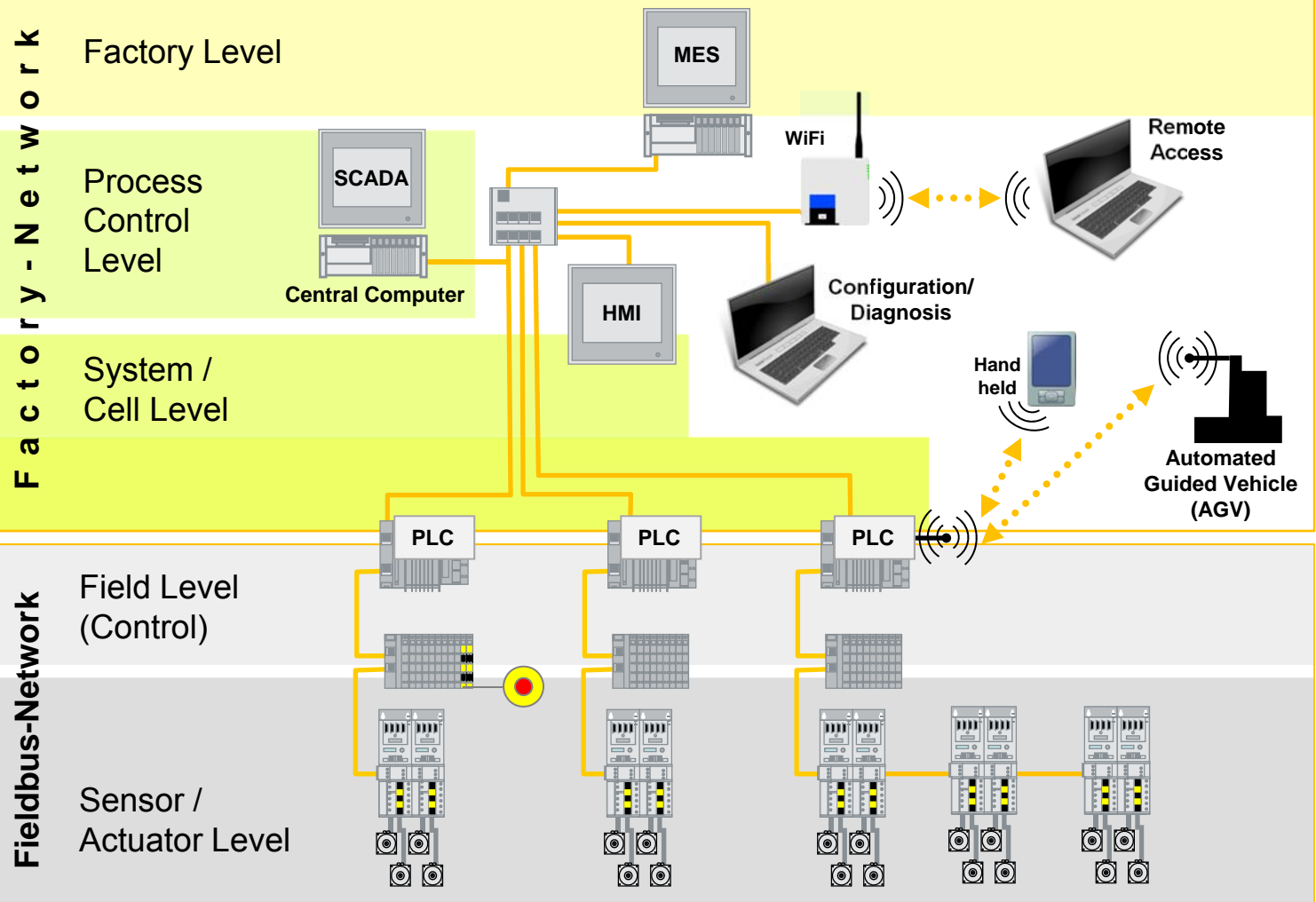
- | Transfer Modes
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Mailbox Kommunikation

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EtherCAT Automation Protocol



EtherCAT Device Protocol (processed on the fly)

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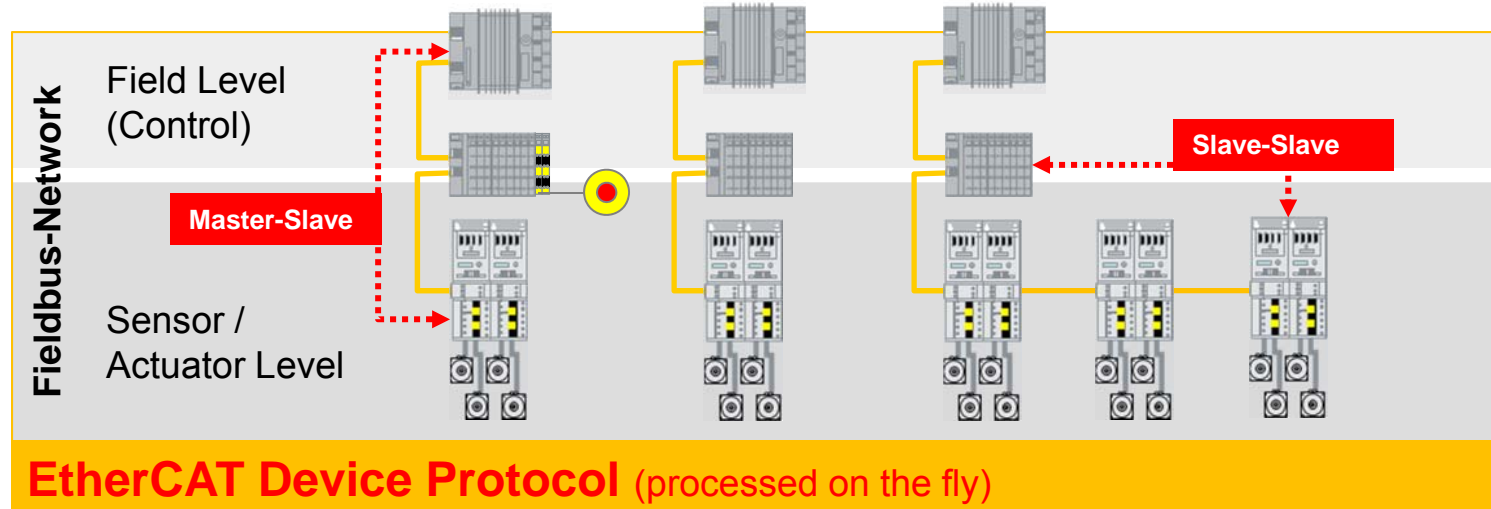
Communication

| Mailbox Data Structure

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Conclusion

- Hard Real-Time
 - Fast Cycle Times within μs
 - Precise Synchronization
- Flexible Topology
 - Line, Tree, Star, Daisy Chain...
- Standard Ethernet Cabling, Cost Effective Components
- Master-Slave & Slave-Slave Communication



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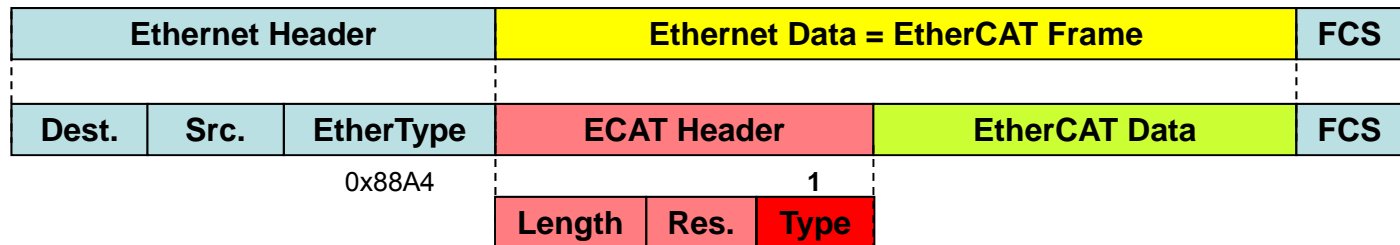
Communication

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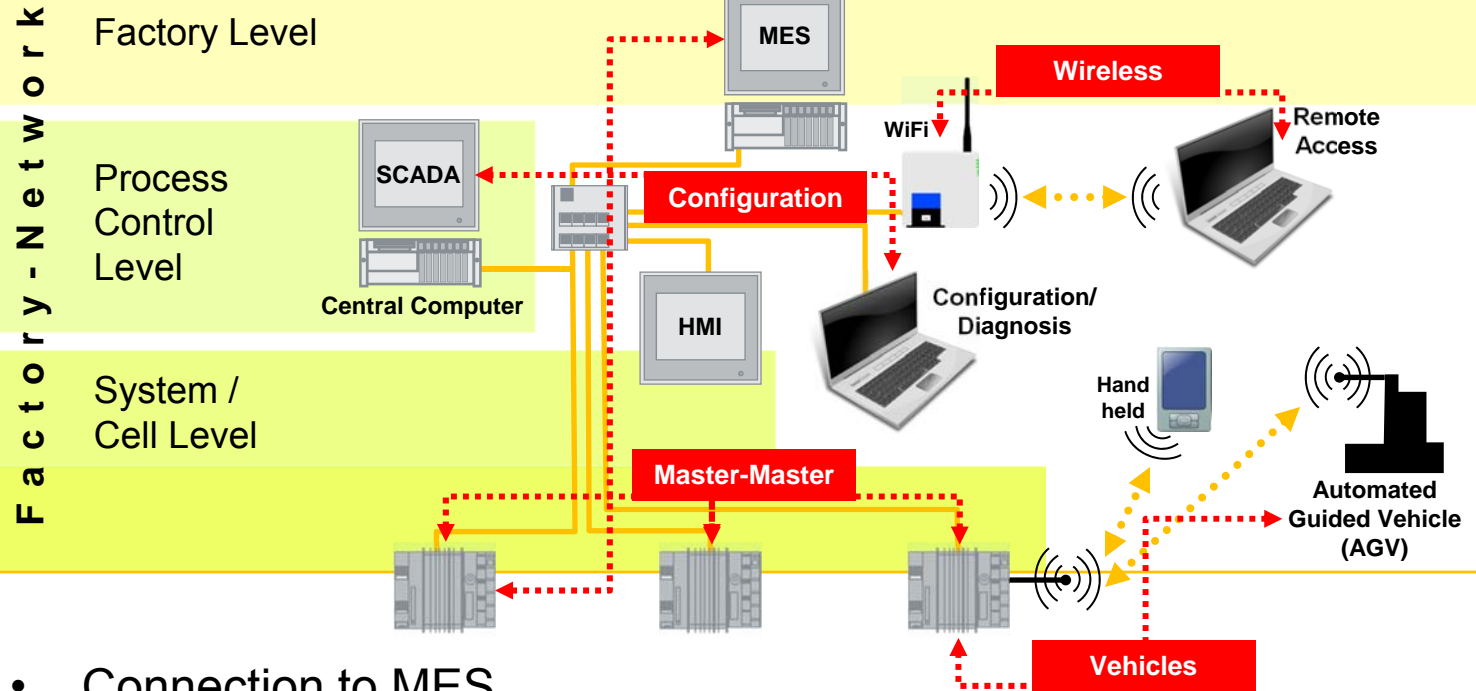
| Object Dictionaries

Conclusion

- Well known „EtherCAT“ Protocol
- Open Protocol: ISO, IEC and SEMI Standard
- Used at field level within machines
e.g. for I/O, Motion, Measurement, Robotics
- Outstanding Features, e.g.:
 - ✓ Hard Real-Time
Protocol is processed in hardware (ESC)
 - ✓ Fast Cycle Times (<100µs)
 - ✓ Precise Synchronization (<100ns)
 - ✓ Flexible Topologies
 - ✓ Standard Ethernet Cabling, Cost Effective Components
- EtherCAT Frame Type = 1



EtherCAT Automation Protocol



- Connection to MES
- Configuration/Diagnosis, also Wireless
- Control/Visualization
- Standard Ethernet Infrastructure Components
- Vehicles/Logistics
- Master-Master Communication

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- Constraints:
 - Standard Ethernet interfaces and infrastructure devices
 - Diagnosis and Configuration
 - No strict requirements regarding cycle time and synchronization
 - Cycle time in the range of milliseconds

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- Communication between:
 - EtherCAT Master Devices (Master-Master Communication)
 - EtherCAT Master and Visualization, Configuration Tool (also via Remote Access)
- Access to devices in underlying EtherCAT segments from the control level
- Access from configuration tools:
 - Configuration of the Master-Master communication
 - Configuration of underlying sub-devices (e.g. Drives, Gateways,...)
 - Routing through EtherCAT Master

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Service	Required Mechanism			
	PD	MBX	R	OD
Master-Master Communication	X			X
External Configuration and Diagnosis		X	X	X
Connection to Main Computer / Controller and MES / ERP Systems	X	X		
Connection to Visualization including Status and Monitoring	X	X		

Abbreviations:

PD Process Data Communication (cyclic)

MBX Mailbox Communication (acyclic)

R Routing

OD Object Dictionary

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- ✓ EtherCAT Automation Protocol (EAP) achieves all these requirements

- ✓ EAP is an enhancement of the EtherCAT technology

IEC61158, Part 12:

EtherCAT Specification

- Protocols

- Frame Structure

ETG.1005:

EAP Specification

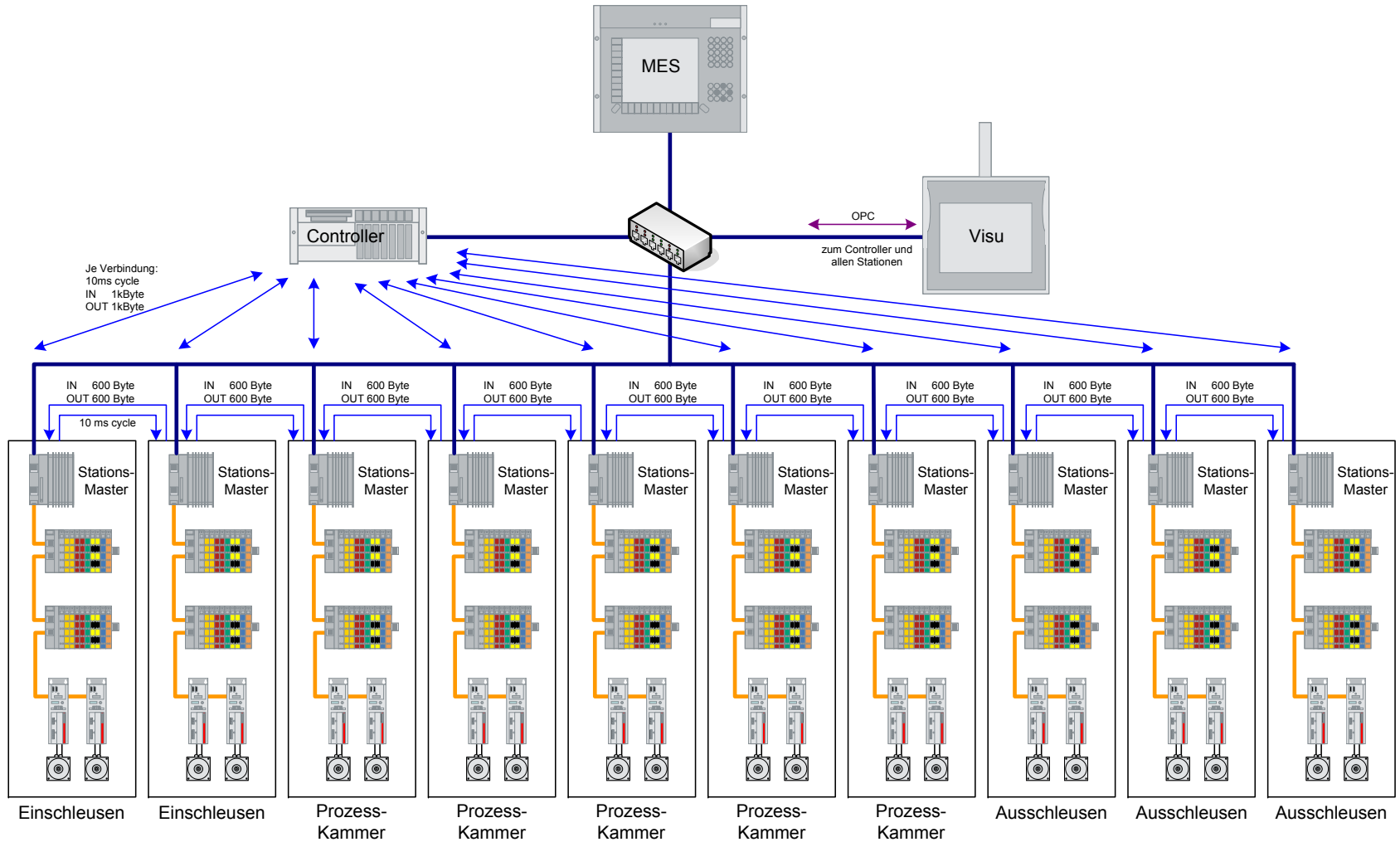
- Configuration Structure

- Network Management Functions

- ✓ EAP offers services for communication at control level and thus for **complete factory networking**

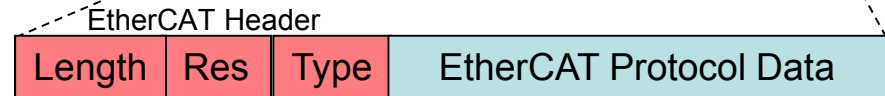
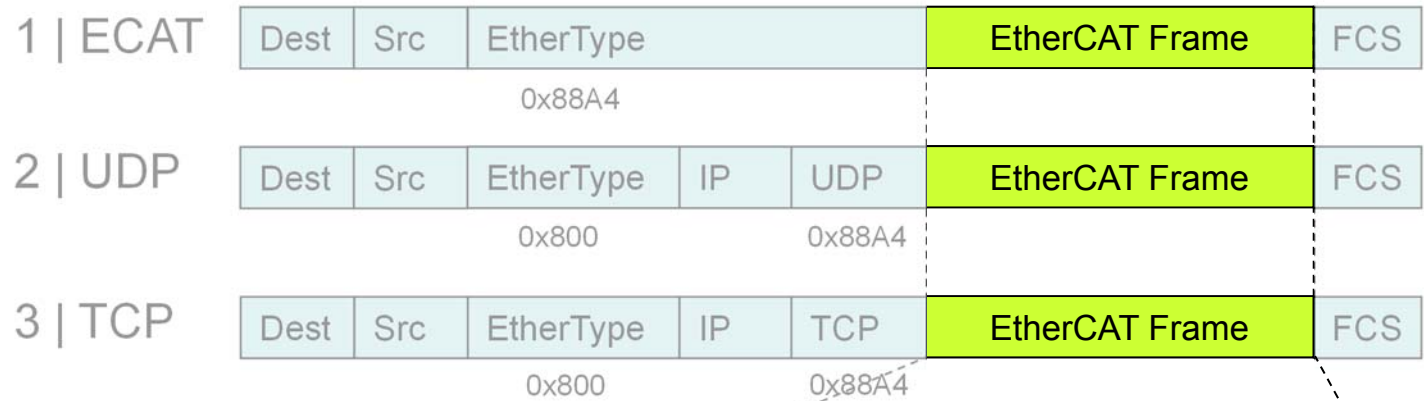


EAP | Example Application



- Ethernet Connection
- EtherCAT Segment
- ↔ EtherCAT Automation Protocol
- ↔ OPC

- Flexible** Protocol Transmission:



- **Standard EtherCAT Frame Header**
- **Standard Frame Structure**

Type 1	EtherCAT Device Protocol
Type 4	EAP Process Data
Type 5	EAP Mailbox Data

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- EAP Process Data communication is used for cyclic data exchange
- An EtherCAT Master can publish information and can receive information from other Master devices
- Two transfer modes
 - Pushed Data Exchange (Broadcast)
 - Polled Data Exchange

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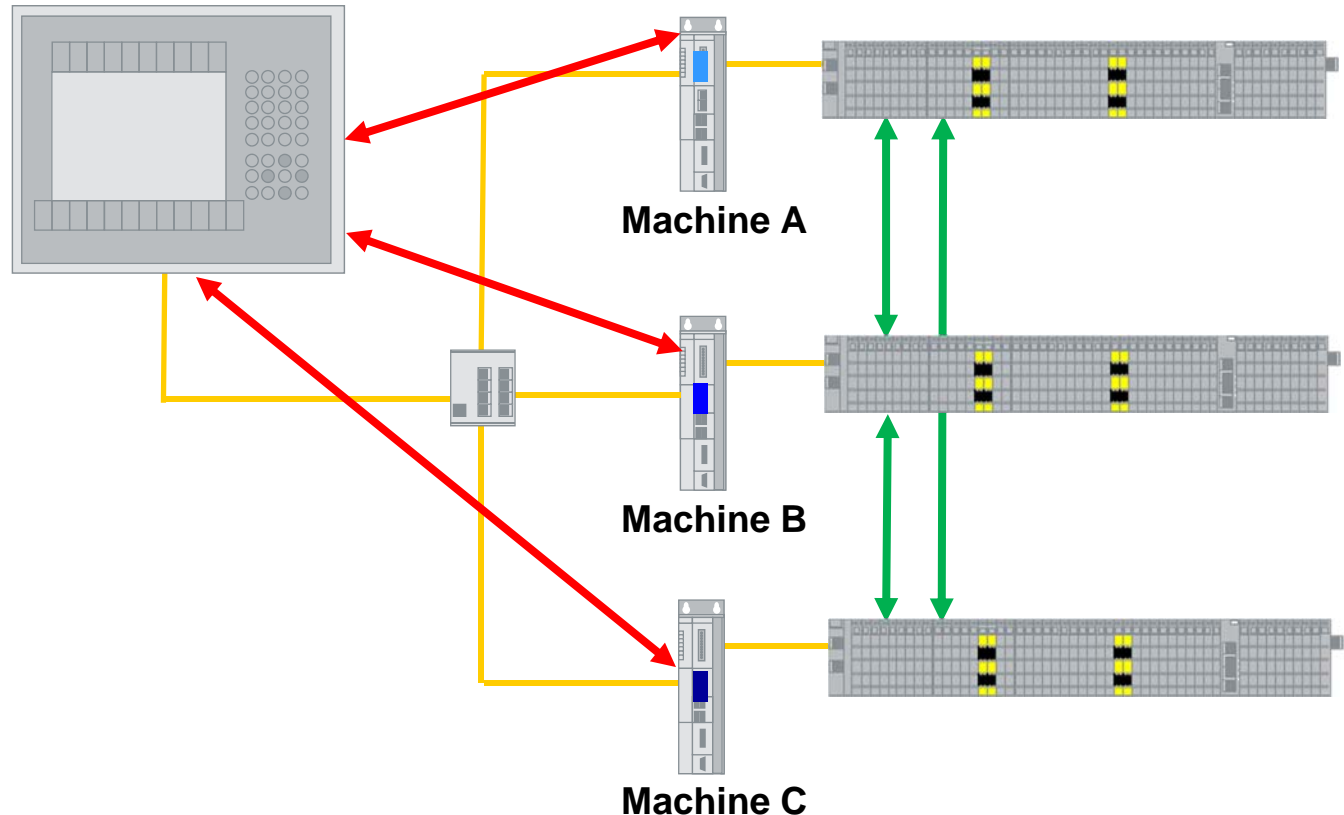
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- **Pushed Data Exchange (Broadcast)**
 - each node can send information with its own cycle
 - all nodes are able to receive information from each other



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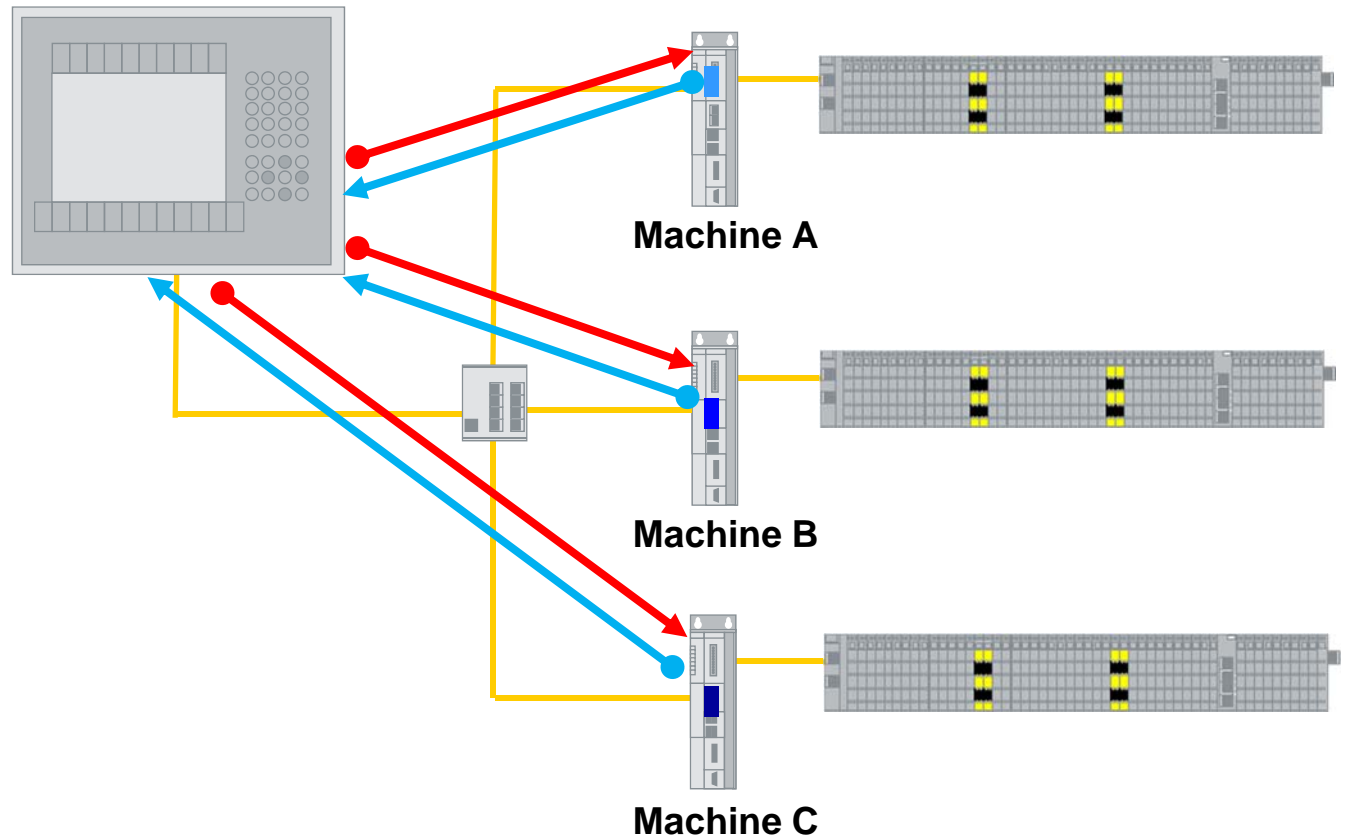
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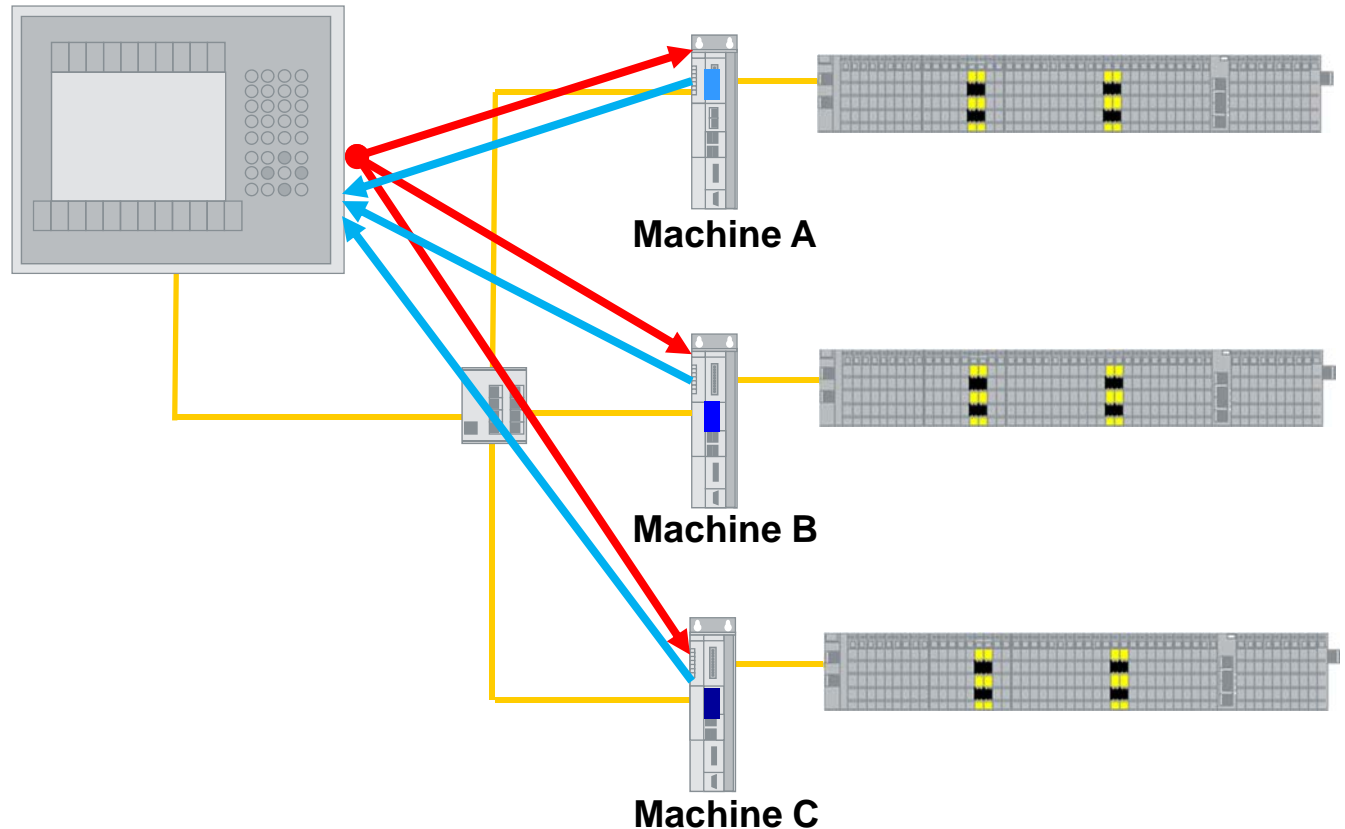
Conclusion

- **Polled Data Exchange (1:1 Connection)**
 - One device sends cyclically its information (Client)
 - Each addressed device (Server) responds with its telegram



- **Polled Data Exchange (1:n Connection)**

- One device sends cyclically its information (Client)
- One or many devices (Server) response with their telegram
- Soft Synchronization of devices



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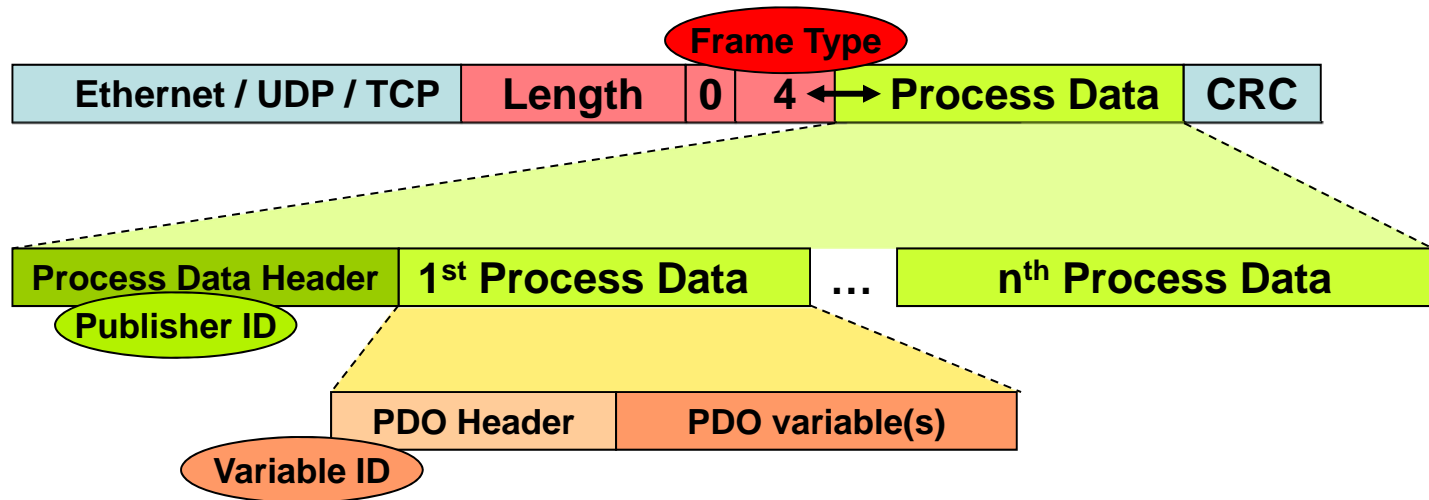
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Conclusion



- EtherCAT Header: ***EtherCAT Frame Type*** = 4
- ***Telegram*** consists of one or several ***Process Data***
- ***Process Data*** consist of one or several ***PDOs***
- ***Publisher ID*** = AoE NetID of Publisher
- Each ***PDO*** consists of one or several ***Variables***
- ***Variable ID*** identifies Process Data
→ **Connectionless**
- Cyclic Frames are **configured in advance**

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- EAP Mailbox Communication is used for asynchronous access to the devices
 - Configuration of Process Data
 - Configuration of Device Specific Parameters
 - Diagnosis Information of EtherCAT Slaves
- Standard Mailbox Protocol in Ethernet telegram (Type: 0x88A4) or UDP/TCP Telegram

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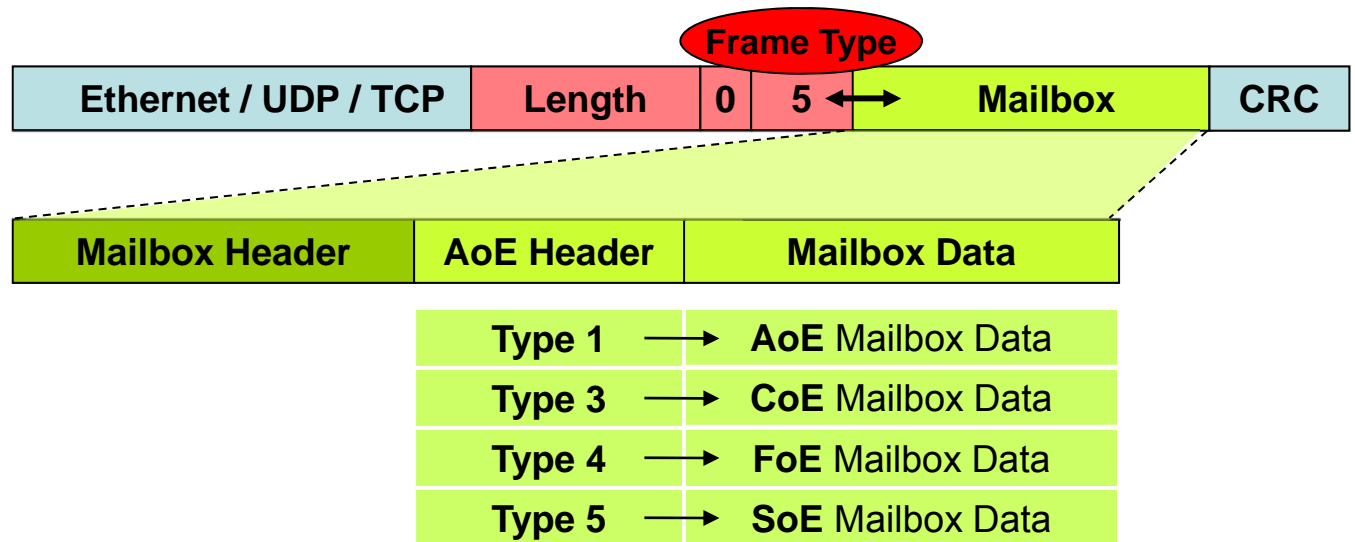
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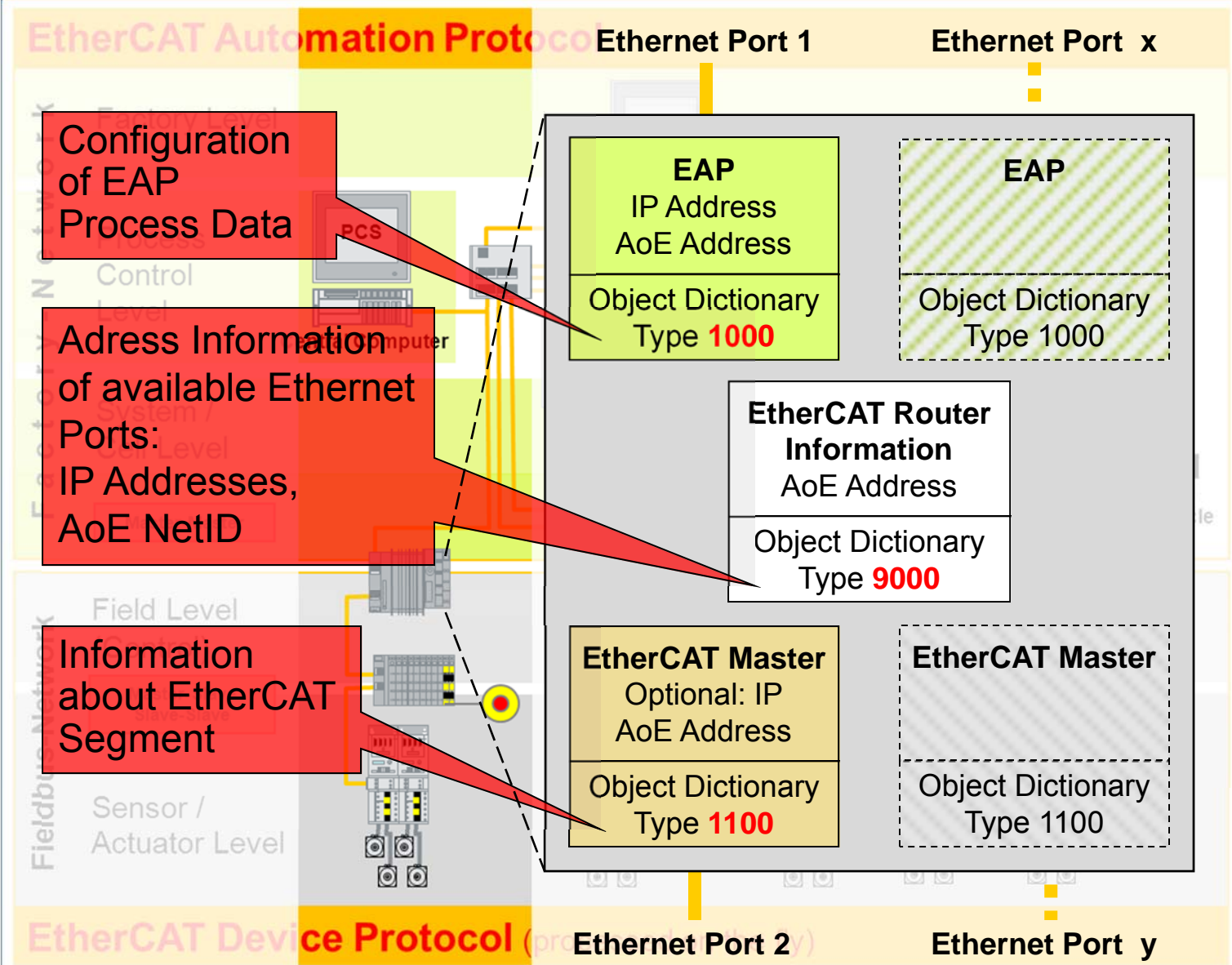
Conclusion

- EtherCAT Header: ***EtherCAT Frame Type*** = 5
 - Indicates mailbox communication
- Telegram consists of a ***Mailbox Header*** and ***Mailbox (Protocol) Data***
- For EAP: ***Mailbox Header Type*** = 1 (AoE)
 - Routable protocol to access several object dictionaries
 - ***AoE Header Type***: Mapping of other Mailbox protocols possible



Object Dictionaries within EtherCAT Master for Configuration and Routing

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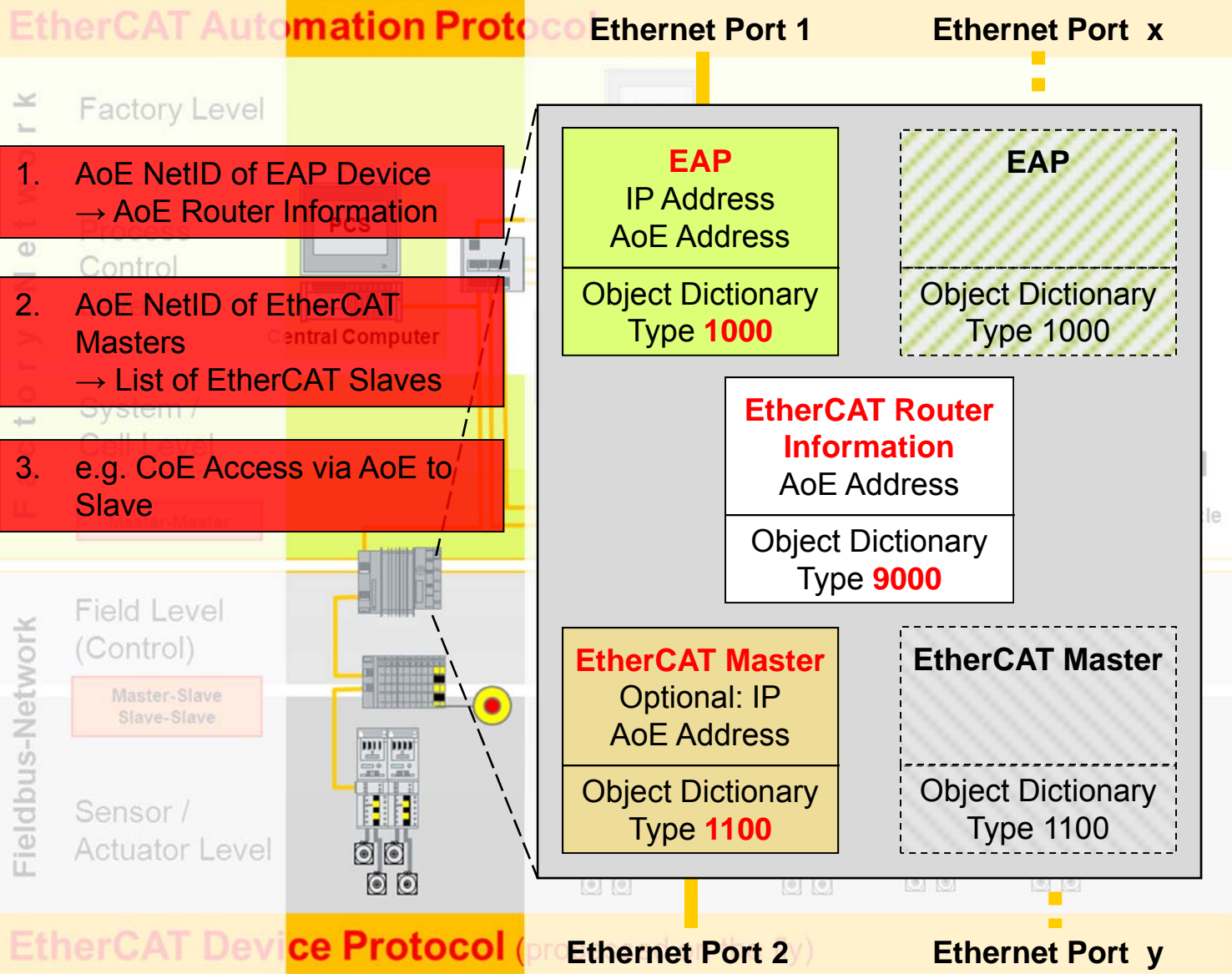


Configuration of EAP Process Data

Address Information of available Ethernet Ports: IP Addresses, AoE NetID

Information about EtherCAT Segment

Access to EtherCAT Slave



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Conclusion

- ✓ Master-Master Communication
- ✓ Remote Configuration / Diagnosis
- ✓ Exchange of Process Data and Parameter Data
- ✓ Routing to any device connected
- ✓ Easy vertical integration
- ✓ Integration of wireless device
- ✓ Data Structure equal to EtherCAT Device Protocol
- ✓ IP Addresses only for Control Level – not for Fieldbus Level

→ EtherCAT is factory networking!

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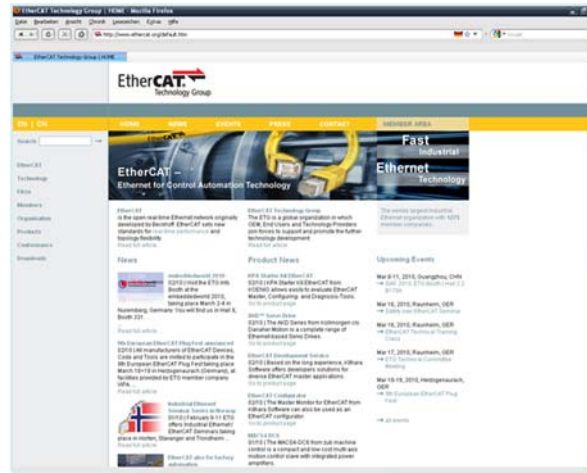
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Please visit
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for more information



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